

Seventh Semester B.E. Degree Examination, Dec.2013/Jan.2014 Image Processing

Time: 3 hrs. Max. Marks:100

Note: Answer FIVE full questions, selecting at least TWO questions from each part.

PART – A

- 1 a. With a neat block diagram, describe various components used in general purpose image processing system. (08 Marks)
 - b. Briefly explain the principle of image formation in Human eye.

(08 Marks)

- c. Let p and q be the pixels at coordinates (5, 5) and (10, 15) respectively. Find out which distance measure gives the minimum distance between the pixels. (04 Marks)
- 2 a. Explain the process of image sampling and quantization in digital image formation.

(10 Marks)

b. Explain: i) False contouring, ii) Checkerboard pattern.

(05 Marks)

Consider the image segment shown in Fig.Q2(c). Let $V = \{2, 3, 4\}$, compute the length of shortest 4-, 8- and m- path between p and q. If any particular path does not exist between these two points, explain why?

(05 Marks)

| | 3 | 4 | 1 | 2 | 0 | |
|-----|---|---|---|---|---|-----|
| | 0 | 1 | 0 | 4 | 2 | (q) |
| | 2 | 2 | 3 | 1 | 4 | |
| (p) | 3 | 0 | 4 | 2 | 1 | |
| | 1 | 2 | 0 | 3 | 4 | |

3 a. Consider a 2×2 transform matrix A and the image U, given below:

$$A = \frac{1}{2} \begin{bmatrix} \sqrt{3} & 1 \\ -1 & \sqrt{3} \end{bmatrix} \qquad U = \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix}$$

Calculate the transformed image V and the basis images. Check the image U using basis images and transformed image V. (10 Marks)

- b. Define Haar transform. Find Haar matrix for N = 8 and explain how it is constructed. State its properties. (10 Marks)
- 4 a. Explain the importance of discrete cosine transform with its equations and properties.

(08 Marks)

b. Write a short note on KL transform.

(06 Marks)

Prove that Hadamard transform is a fast transform.

(06 Marks)

PART - B

5 a. Consider 8-level grey scale image of size 8 × 8 shown in Fig.Q5(a). Show histogram of the image. Compute equalized histogram and display graphically. (10 Marks)

| 0 | 1 | 1_ | 0 | 0 | 1 | 1 | 0 |
|---|---|----|---|---|---|---|---|
| 0 | 1 | 2 | 3 | 3 | 2 | 1 | 0 |
| 0 | 4 | 5 | 3 | 3 | 5 | 4 | 0 |
| 0 | 1 | 2 | 7 | 7 | 2 | 1 | 0 |
| 0 | 1 | 2 | 6 | 6 | 2 | 1 | 0 |
| 0 | 4 | 5 | 3 | 3 | 5 | 4 | 0 |
| 0 | 1 | 2 | 3 | 3 | 2 | 1 | 0 |
| 0 | 1 | 1 | 0 | 0 | 1 | 1 | 0 |

Fig.Q5(a)

- 5 b. Using the second derivative, develop a Laplacian mask for image sharpening. (06 Marks)
 - c. Explain in brief any point processing technique implemented in image processing. (04 Marks)
- 6 a. Discuss the characteristics of high boost filter for both frequency and spatial domain. Explain how high boost filtering increases the enhancement of the image. (10 Marks)
 - b. With the help of block diagram, explain homomorphic filters for image enhancement.

(10 Marks)

(06 Marks)

- 7 a. Explain different image degradation models.
 - b. Explain in brief, the inverse filtering approach and its limitations. Explain how the limitations can be overcome using Wiener filtering. (10 Marks)
 - c. What is an order statistics filter? Explain any one such filter. (04 Marks)
- 8 a. Explain the following color models:
 - i) RGB color model
 - ii) HSI color model (10 Marks)
 - b. Write steps involved in converting colors from HSI to RGB. (05 Marks)
 - c. Explain pseudo color image processing in brief. (05 Marks)

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